

Dynamic Logic of Product Relation Changers

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DaLi2025 @ Shaanxi Normal University
21st Oct. 2025

State-deletion vs Link-deletion

- Two primary approaches for handling agents' knowledge & belief change.
- **State-deletion** (or domain restriction)
 - ▶ **PAL** (Plaza, 1979)
 - ▶ **DEL** (Baltag et al., 1998)
- **Link-deletion** (or accessibility change)
 - ▶ **PAL** (Gerbrandy & Groeneveld, 1997)
 - ▶ **AUL** & **GAUL** (Kooi & Renne, 2011)
 - ▶ **DLRC** (van Benthem & Liu, 2007)
- In this talk, we focus on a **link-deletion** approach!

Link-deletion Approach

“ PAL ”-style	AUL (Kooi & Renne, 2011)	DLRC (van Benthem & Liu, 2007)
“ DEL ”-style	GAUL (Kooi & Renne, 2011)	?

- **Arrow Update Logic** restricts a 's accessibility to the one from φ -worlds to ψ -worlds.
- **Dynamic Logic of Relation Changers** changes a 's accessibility by a program in iteration-free **PDL**.
 - ▶ Generalizes **AUL**.
- **Generalized AUL** expands **AUL** with action models and has the same expressivity as **DEL**.

Motivation

We integrate the notions of relation changers and action models within a unified framework.

PRC: Dynamic logic of product relation changers

- generalizes both relation changers & (generalized) arrow updates.
- has sound & complete axiomatization
(inside-out strategy using recursion axioms).
- also has cut-free labelled sequent calculus.

Outline

- 1 Dynamic Logic of Relation Changers (**DLRC**)
- 2 Dynamic Logic of Product Relation Changers (**PRC**)
- 3 Labelled Sequent Calculus for **PRC**

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Syntax for **DLRC**

Language $\mathcal{L}^+$ for **DLRC**

(= iteration-free **PDL** + relation changers **r**):

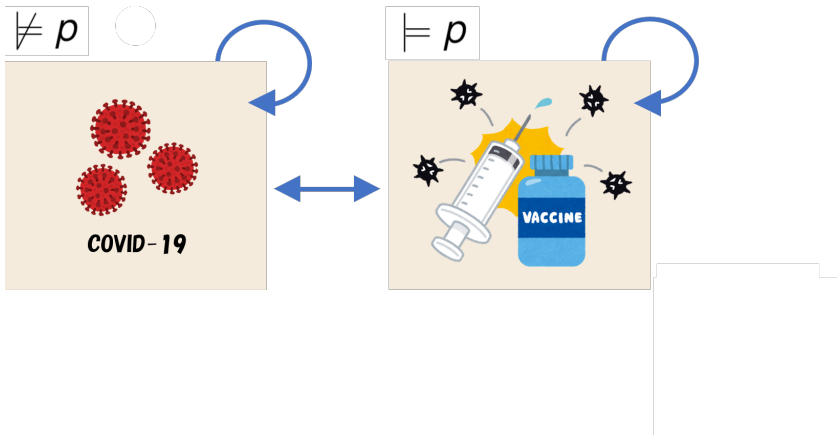
$$\text{FORM}_{\mathcal{L}^+} \ni \varphi ::= p \mid \neg\varphi \mid (\varphi \rightarrow \varphi) \mid [\alpha]\varphi \mid [\mathbf{r}]\varphi,$$
$$\text{PR}_{\mathcal{L}^+} \ni \alpha ::= a \mid (\alpha \cup \alpha) \mid (\alpha; \alpha) \mid ?\varphi,$$
$$\text{RC}_{\mathcal{L}^+} \ni \mathbf{r} ::= (\mathbf{a} := \alpha_a)_{a \in \mathbf{AP}},$$

where $p \in \mathbf{P}$ & $a \in \mathbf{AP}$ (atomic programs).

- $[\mathbf{r}]\varphi$: “After changing an accessibility relation for each program a by α_a , φ holds.”
- We also use $\mathbf{r}(a)$ to mean α_a .

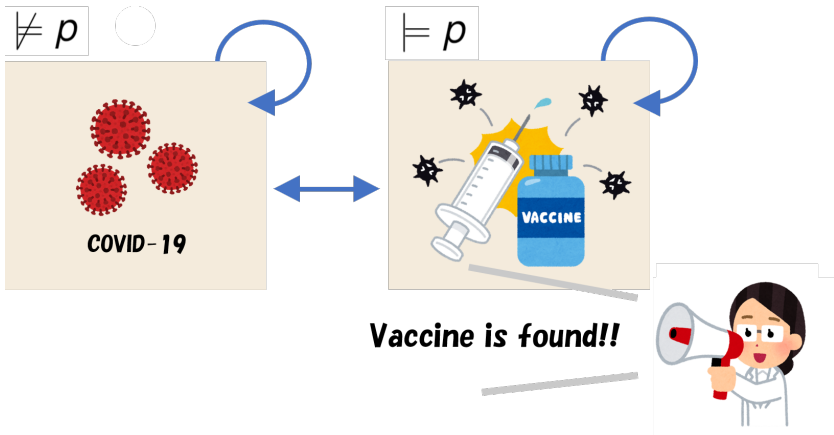
Introspective Ann. $[r!_p]$ (van Ditmarsch et al. 2007)

Let p be “COVID-19 vaccine is available.”



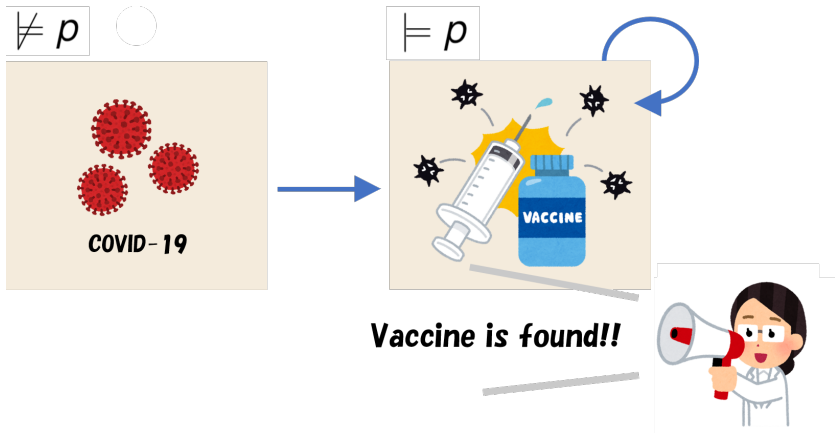
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Introspective Ann. $[r!_p]$ (van Ditmarsch et al. 2007)

Let p be “COVID-19 vaccine is available.”



$$r!_p = (a := a; ?p)_{a \in \mathbf{AP}}$$

Other Examples of Relation Changers

Atomic Programs Exchange: Let $\mathbf{AP} = \{a, b, c\}$.

$$r := (a := b, b := c, c := a).$$

Preference Upgrade:

$$r_{\# \varphi} := (a := (? \neg \varphi; a) \cup (a; ? \varphi))_{a \in \mathbf{AP}}$$

Arrow Updates: Let $U \subseteq \text{FORM}_{\mathcal{L}} \times \mathbf{AP} \times \text{FORM}_{\mathcal{L}}$.

$$r_{*U} := \left(\textcolor{red}{a} := \bigcup_{(\varphi, \textcolor{red}{a}, \psi) \in U} (? \varphi; \textcolor{red}{a}; ? \psi) \right)_{\textcolor{red}{a} \in \mathbf{AP}}$$

Semantics for **DLRC**

Given any $\mathfrak{M} = (W, (R_a)_{a \in \mathbf{AP}}, V)$ & any $w \in W$,

$$\begin{aligned} \mathfrak{M}, w \models [\alpha]\varphi & \text{ iff } \mathfrak{M}, v \models \varphi \text{ for all } v \text{ with } wR_\alpha v, \\ wR_{\alpha \cup \beta} v & \text{ iff } wR_\alpha v \text{ or } wR_\beta v, \\ wR_{\alpha; \beta} v & \text{ iff } wR_\alpha u \text{ and } uR_\beta v \text{ for some } u \in W, \\ wR_{?\varphi} v & \text{ iff } w = v \text{ and } \mathfrak{M}, v \models \varphi, \\ \mathfrak{M}, w \models [r]\varphi & \text{ iff } \mathfrak{M}^r, w \models \varphi, \end{aligned}$$

where $\mathfrak{M}^r = (W, (R_a^r)_{a \in \mathbf{AP}}, V)$ and

$R_a^r := R_{r(a)}$ where recall that $r(a)$ is a program.

van Benthem & Liu 2007

There is a complete axiomatization of **DLRC**.

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Action Model for Public Ann. of φ

$$\mathbb{E} = (\mathbf{E}, (Q_a)_{a \in \text{AP}}, \text{pre})$$

- Let $\mathbf{E} = \{e\}$, $Q_a = \{(e, e)\}$, and $\text{pre}(e) = \varphi$.

What is a single event “action model” of one relation changer r , say, preference upgrade $r_{\# \varphi}$?

Action Model for Preference Upgrade

$$r_{\# \varphi} := (a := (? \neg \varphi; a) \cup (a; ? \varphi))_{a \in \mathbf{AP}}$$

$$\mathbb{E} = (\{ \mathbf{e} \}, (\{ (e, e) \})_{a \in \mathbf{AP}}, \boxed{?_1}, \boxed{?_2})$$

- $\boxed{?_1}$: a generalization of pre should include both φ and $\neg \varphi$.
- $\boxed{?_2}$ should capture program constructions $r_{\# \varphi}(a)$.

Action Model for Preference Upgrade

$$r_{\# \varphi} := (a := (? \neg \varphi; a) \cup (a; ? \varphi))_{a \in \mathbf{AP}}$$

$$\mathbb{E} = (\{e\}, (\{(e, e)\})_{a \in \mathbf{AP}}, \boxed{?_1}, \boxed{?_2})$$

- $\boxed{?_1}$: a generalization of pre should include both φ and $\neg \varphi$.
 $\leadsto \mathbf{CND}(e) = (\varphi, \neg \varphi).$
- $\boxed{?_2}$ should capture program constructions $r_{\# \varphi}(a)$.
 $\leadsto \mathbf{rel}_a(e, e) = (\neg \varphi; a) \cup (a; \varphi).$

Modified Action Model

$$\mathbb{E} = (\mathbf{E}, (Q_a)_{a \in \mathbf{AP}}, (\text{CND}(\mathbf{e}))_{\mathbf{e} \in \mathbf{E}}, (\text{rel}_a)_{a \in \mathbf{AP}})$$

- $\text{CND}(\mathbf{e})$: a finite list of formulas (generalization of pre conditions).
- rel_a : sends each $(\mathbf{e}, \mathbf{f}) \in Q_a$ to a program $\alpha_{(\mathbf{e}, \mathbf{f})}$ s.t.

$$\alpha_{(\mathbf{e}, \mathbf{f})} ::= b \mid ?\varphi_{\mathbf{e}} \mid ?\varphi_{\mathbf{f}} \mid (\alpha \cup \alpha) \mid (\alpha; \alpha),$$

where $b \in \mathbf{AP}$, $\varphi_{\mathbf{e}} \in \text{CND}(\mathbf{e})$, & $\varphi_{\mathbf{f}} \in \text{CND}(\mathbf{f})$.

We also use $\alpha_{(a, \mathbf{e}, \mathbf{f})}$ to mean $\text{rel}_a(\mathbf{e}, \mathbf{f})$.

Syntax for **PRC**

Language $\mathcal{L}^\otimes$ for **PRC**

(= iteration-free **PDL** + modified action models $\mathbb{E}$):

$$\text{FORM}_{\mathcal{L}^\otimes} \ni \varphi ::= p \mid \neg\varphi \mid (\varphi \rightarrow \varphi) \mid [\alpha]\varphi \mid [\mathbb{E}, e]\varphi,$$
$$\text{PR}_{\mathcal{L}^\otimes} \ni \alpha ::= a \mid (\alpha \cup \alpha) \mid (\alpha; \alpha) \mid ?\varphi,$$
$$\text{AM}_{\mathcal{L}^\otimes} \ni \mathbb{E} ::= (\mathbf{E}, (Q_a)_{a \in \mathbf{AP}}, (\text{CND}(e))_{e \in \mathbb{E}}, (\text{rel}_a)_{a \in \mathbf{AP}}),$$

where $p \in \mathbf{P}$, $a \in \mathbf{AP}$ and $\mathbb{E}$ is a **modified** action model.

Semantics for **PRC**

Given any $\mathfrak{M} = (W, (R_a)_{a \in \mathbf{AP}}, V)$ & any $w \in W$,

$$\mathfrak{M}, w \models [\mathbb{E}, e]\varphi \quad \text{iff} \quad \mathfrak{M}^{\otimes \mathbb{E}}, (w, e) \models \varphi,$$

where $\mathfrak{M}^{\otimes \mathbb{E}} = (W^{\otimes \mathbb{E}}, (R_a^{\otimes \mathbb{E}})_{a \in \mathbf{AP}}, V^{\otimes \mathbb{E}})$ and

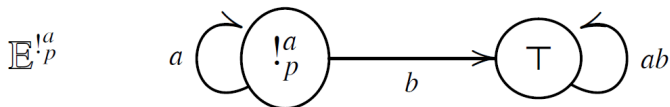
$$\begin{aligned} W^{\otimes \mathbb{E}} &:= W \times \mathbb{E}, \\ (w, e) R_a^{\otimes \mathbb{E}} (v, f) &\text{ iff } w R_{\alpha_{(a, e, f)}} v \text{ and } e Q_a f, \\ (w, e) \in V^{\otimes \mathbb{E}}(p) &\text{ iff } w \in V(p), \end{aligned}$$

recall that $\alpha_{(a, e, f)} := \text{rel}_a(e, f)$.

Private Announcement $[!^a_\varphi]$

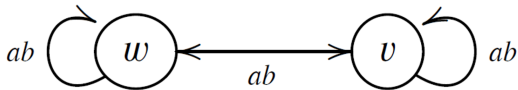
“a alone was privately told that p .”

Let $\mathbf{AP} = \{a, b\}$.



- $\text{CND}(!^a_p) := p$ and $\text{CND}(T) := T$,
- $\text{rel}_c(e, f) := c; ?\text{CND}(f)$ for all $(e, f) \in Q_c$.

M



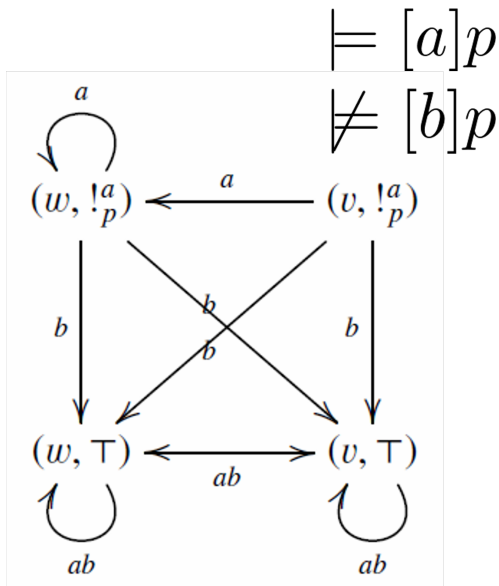
$$\models p$$

$$\not\models p$$

$$\not\models [a]p$$

$$\not\models [b]p$$

$$\mathfrak{M} \otimes \mathbb{E}^a_p$$



Hilbert System HPRC

Hilbert system of iteration-free **PDL** (Harel et al. 2000) and:

$$\begin{array}{ll} ([\mathbb{E}, e] \mathbf{at}) & [\mathbb{E}, e]p \leftrightarrow p \\ ([\mathbb{E}, e] \neg) & [\mathbb{E}, e]\neg\varphi \leftrightarrow \neg[\mathbb{E}, e]\varphi \\ ([\mathbb{E}, e] \rightarrow) & [\mathbb{E}, e](\varphi \rightarrow \psi) \leftrightarrow ([\mathbb{E}, e]\varphi \rightarrow [\mathbb{E}, e]\psi) \\ ([\mathbb{E}, e][a]) & [\mathbb{E}, e][a]\varphi \leftrightarrow \bigwedge_{f \in Q_a(e)} [\alpha_{(a,e,f)}][\mathbb{E}, f]\varphi \\ ([\mathbb{E}, e][\cup]) & [\mathbb{E}, e][\alpha \cup \beta]\varphi \leftrightarrow [\mathbb{E}, e][\alpha]\varphi \wedge [\mathbb{E}, e][\beta]\varphi \\ ([\mathbb{E}, e][;]) & [\mathbb{E}, e][\alpha; \beta]\varphi \leftrightarrow [\mathbb{E}, e][\alpha][\beta]\varphi \\ ([\mathbb{E}, e][?]) & [\mathbb{E}, e][?\psi]\varphi \leftrightarrow [\mathbb{E}, e](\psi \rightarrow \varphi) \\ (\text{Nec}_{[\mathbb{E}, e]}) & \text{From } \varphi, \text{ infer } [\mathbb{E}, e]\varphi \end{array}$$

We can also derive recursion axioms for **GAUL**.

Completeness of **HPRC**

Theorem

φ is a theorem of **HPRC** iff φ is valid on all models.

($\therefore$) By reducing the completeness of **HPRC**
to that of iteration-free **PDL** via recursion axioms.

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Labelled Formalism for **PDL** (Maffezioli & Naibo 2013)

$\text{VAR} = \{x, y, \dots\}$: a countably infinite set of **variables**.

$$x : \varphi$$

“A formula φ holds at state x ”

$$xR_{\alpha}y$$

“There is an α -link from x to y ”
(α : **program**)

$$x = y$$

“State x equals state y ”

Labelled Formalism for **PRC**

$\text{VAR} = \{x, y, \dots\}$: a countably infinite set of **variables**.

$$x : ((\mathbb{E}_1, \mathbf{e}_1), \dots, (\mathbb{E}_n, \mathbf{e}_n)) \varphi$$

$$(x, ((\mathbb{E}_1, \mathbf{e}_1), \dots, (\mathbb{E}_n, \mathbf{e}_n))) \mathbf{R}_\alpha (y, ((\mathbb{E}_1, \mathbf{f}_1), \dots, (\mathbb{E}_n, \mathbf{f}_n)))$$

$$x = y$$

Labelled Sequent Calculus GPRC

A sequent is a pair (Γ, Δ) of
finite multisets of labelled expressions in **PRC**.

$$\Gamma \Rightarrow \Delta$$

“if all of Γ hold, then some of Δ holds”

Based on these definitions,
we define rules of labelled sequent calculus **GPRC**.

Features of GPRC

- It can be regarded as a natural generalization of **GDLRC** for **DLRC**. (H. et al., 2016)
- Equality rules are adopted from (Seligman, 2001) for hybrid logic.
- The following are key theorems:

If φ is a theorem of **GPRC**, then φ is valid on all models.

All theorems of **HPRC** are also theorems of **GPRC**.

Cut-elimination holds for **GPRC**.

Conclusion

“ PAL ”-style	AUL (Kooi & Renne, 2011)	DLRC (van Benthem & Liu, 2007)
“ DEL ”-style	GAUL (Kooi & Renne, 2011)	Our work!

Main Theorem

TFAE:

- 1 φ is valid on all models,
- 2 φ is a theorem of **HPRC**,
- 3 φ is a theorem of **GPRC**,
- 4 φ is a theorem of **GPRC** w/o (Cut).

Further Directions

- Explore relationship between General Dynamic Dynamic Logic (Girard et al., 2012) and **PRC**.
- Investigate an alternative semantics of **PRC**
(cf. update universe by (van Benthem, 2014)).
- Constructive generalization of **PRC**.

Thank you!